Course: B. Tech in Electrical Engineering Sem: IV

Subject Code: BTEEPE405B

Subject Name: Signals & System

Unit-1

- (1) Find the energy and power of following Signal/Sequence

 (i) x[n] = 2ⁿ u[-n]
 (ii) x(t) = Rect t/T
 (iii) ∫_{-∞}[∞] {δ(t)Cos2t + δ(t 2)Sin2t}dt
 (iv) ∫₋₀^{2π} {t Sint δ(π/2 t)}dt

 (2) Sketch the following signals:
 - (i) u[n+2]u[-n+3] (ii) -2u(t+2) (iii) $\pi(t-2)$
- (3) If $X[n] = \{1,2,3,4,1\}$, then: Find x[2n-3] and plot x[2n/3] and plot x[-2n]
- (4) Plot x(2t + 1) and x(2 3t) from the following signal:



- (5) Check for the periodicity of following signals and find the fundamental time period if they are periodic:
 - (i) $x[n] = e^{j2\pi n+2}$
 - (ii) $x(t) = 2 + \sin(2t) + \cos(3\pi t)$
 - (iii) $x(t) = 2u(t) + Sin^{2}(3\pi t)$
 - (iv) $x(n) = (\frac{1}{2})^n u[n]$

<u>Unit-2</u>

- 1. Define systems. Write the properties of the systems.
- 2. Check the following systems for Static/Dynamic/Causal/Non-Causal

(i)
$$y[n] = 2x[n+1] + 3x[n] - x[n-1]$$
 (ii) $y(t) = \frac{dx(t)}{dx} + x^2(t) + x(t+1)$

- **3**. Explain the process of checking linearity property of the system in detail.
- 4. Check whether the following systems are Stable/Unstable.

(i) y(t) = t.x(t)(ii) y(t) = u(t) + 2(iii) y(t) = sin(t).u(t)(iv) y(t) = x(t)/t

5. Describe the causal and non-causal systems

<u>Unit-3</u>

- 1. Define transfer function and write the properties of LTI system.
- 2. write the properties of convolution.
- **3**. Find the convolution of following signals

(i) x(t) = u(t)-u(t-2) and y(t) = u(t)-u(t-1)(ii) x(t) = rect(t/T) and $y(t) = \Delta(t/T)$ (iii) x(t) = u(t+5) and $y(t) = \delta(t-7)$ (iv) x(t) = u(t) and y(t) = 2u(t+2)-3u(t+1)+u(t-2)

4. How the causality and stability of the system can be checked by impulse response of the system explain in detail.

Unit-4

1. Find the Laplace transform of following signals and define ROC.

(i) x(t) = u(t). $e^{(-2t+1)}$ (ii) $x(t) = \sin 2t$. e^{2t} . u(2t)(iii) x(t) = u(t)- u(2t-1)(iv) $x(t) = [t^2+3t-7]$. u(t-1)(v) x(t) = t. sint. u(t)

2. Find the impulse response in time domain of the following systems, if systems are stable and causal.

(i) H(S) = ln
$$\left(\frac{S+5}{S+6}\right)$$

(ii) H(S)= $\frac{2S+5}{S^2+5S+6}$
(iii) H(S)= $6S^2 + 1$

3. Consider a Continuous time LTI system for which input x(t) and output $y(t \text{ are related by the following differential equation$

$$\frac{d^2y(t)}{dt^2} - \frac{dy(t)}{dt} - 2y(t) = x(t)$$

Determine h(t)

(1) When system is Causal

(ii) When the system is stable

(iii) When the system is neither causal nor stable

4. Find Z- transform of following signals, and comment on ROC.

(i) $x[n] = \{1,2,3\}$ (ii) $x[n] = 3^{n} u[n] - 2^{n} u[-n-1]$ (iii) x[n] = Sgn [n](iv) $x[n] = 2^{|n|}$ (v) $x[n] = (\frac{1}{2})^{n} u[-n-1]$

5. Consider a LTI system with following input output relationship: $Y[n] = (\frac{1}{2})$. y[n-1] = x[n] - 2 x [n-1]Calculate:

(i) system function.

(ii) output y[n] for input x[n] = u[n]

<u>Unit-5</u>

1. Derive the relation between Laplace transform and Fourier transform.

2. Find the Fourier transform of following signals and plot the magnitude and Fourier spectrum:

(i) $x(t) = e^{-at} u(t)$; a>0(ii) $x(t) = e^{at} u(-t)$; a>0(iii) $x(t) = \delta(t)$ (iv) x(t) = A.Rect(t/T)(v) x(t) = sgn(t)

3. For x(t) shown in figure:



Find:

(i)
$$\int_{-\infty}^{\infty} X(\omega) d\omega$$

(ii) X(o)
(iii) $\int_{-\infty}^{\infty} X(\omega) e^{j4\omega} d\omega$

4. Let x(t) be a periodic signal with fundamental time period 'T' and fourier series coefficient a_k. Derive the fourier series coefficient of each of the following signals in terms of a_k.
(i) x(t-t_0)+x(t+t_0)
(ii) Even{x(t)}
(iii) Real{x(t)}
(iv) x(3t-1)

5. Find Fourier series coefficient of $x(t) = \sum_{m=-\infty}^{\infty} \delta(t - mT)$